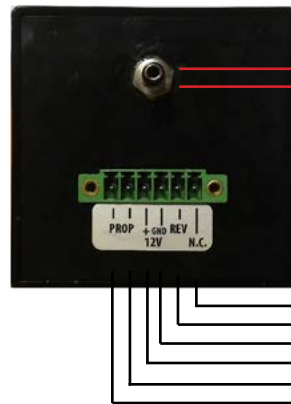


## DUAL MODE GOVERNOR QUICK REFERENCE



- A= Mode Selection switch  
MDP Driven  
Manual  
Constant RPM
- B= Increase/decrease RPM knob  
(only CONSTANT RPM mode)
- C= Increase/decrease RPM switch  
(only manual mode)
- D= OLED DISPLAY

### Connections



MAP (FROM ENGINE)  
4mm tube is required.  
4mm to 6mm joint and 6mm T joint  
is provided

NOT CONNECTED  
RPM Signal  
12V GROUND (-)  
12V +  
PROPELLER MOTOR

- At power on, the governor move the propeller until the minimum pitch.
- OVERCURRENT error over 3 Ampere of current consumption.
- 5A time delayed fuse inside
- Control range: from 4000 to 5500 RPM (for Rotax engines)
- For installation, check the User Guide

### First Setup

SET ENGINE  
ROTAX 912  
UL (80 Hp)

Power on the Governor keeping pressed C switch (down position) for 5 seconds  
Pressing switch C (up position) for 2 second will rotate the available engines.  
When the right engine is displayed, prese switch C in down position for 15 seconds until OK will appear on the screen

### MDP DRIVING Mode

5200 ↑  
MDP map 28.2

Full Automatic mode: the display show the TARGET RPM calculated by the microprocessor and the Governor move the propeller motor in order to achieve the target RPM.  
A flashing arrow means that the governor are driving the motor. A empty fixed arrow means that an end run switch is reached  
In lower left corner the MAP measurement is displayed

### MANUAL Mode

4200 ↑  
MAN 0.0 A

In the Manual mode the motor of the propeller is driven directly from C Switch without any control of microprocessor.  
C switch UP = + RPM = -Pitch  
C switch DOWN = - RPM = + Pitch  
The display show the real RPM. When the propeller motor is moving, a measurement of current consumption in showed, for diagnostic pourpose.

### CONSTANT RPM Mode

5200 ↑  
CNST MAP 28.2

By turning the B knob, pilot can move the target RPM. The display show the target RPM and the Governor move the propeller motor in order to achieve the target RPM.  
A flashing arrow means that the governor are driving the motor. A empty fixed arrow means that that an end run switch is reached  
In lower left corner the MAP measurement is displayed

### Automatic take-off

5200  
CNST TAKE-OFF

MDP DRIVING Mode / CONSTANT RMP Mode  
After power on and for only 1 time, when the governor read a RPM equal to 5000, automatically enter in TAKE-OFF mode.  
In this mode, the microprocessor add 300 RPM to the target for 3 minutes in order to reach a maximun of 5800 RPM instead of 5500 (for Rotax engines).